NAG Library Routine Document

G05RYF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

1 Purpose

G05RYF sets up a reference vector and generates an array of pseudorandom numbers from a multivariate Student's t distribution with ν degrees of freedom, mean vector a and covariance matrix $\frac{\nu}{\nu-2}C$.

2 Specification

```
SUBROUTINE G05RYF (MODE, N, DF, M, XMU, C, LDC, R, LR, STATE, X, LDX, IFAIL)

INTEGER MODE, N, DF, M, LDC, LR, STATE(*), LDX, IFAIL

REAL (KIND=nag_wp) XMU(M), C(LDC,M), R(LR), X(LDX,M)
```

3 Description

When the covariance matrix is nonsingular (i.e., strictly positive definite), the distribution has probability density function

$$f(x) = \frac{\Gamma\left(\frac{(\nu+m)}{2}\right)}{(\pi \nu)^{m/2} \Gamma(\nu/2) |C|^{\frac{1}{2}}} \left[1 + \frac{(x-a)^{\mathsf{T}} C^{-1} (x-a)}{\nu}\right]^{\frac{-(\nu+m)}{2}}$$

where m is the number of dimensions, ν is the degrees of freedom, a is the vector of means, x is the vector of positions and $\frac{\nu}{\nu-2}C$ is the covariance matrix.

The routine returns the value

$$x = a + \sqrt{\frac{\overline{\nu}}{s}}z$$

where z is generated by G05SKF from a Normal distribution with mean zero and covariance matrix C and s is generated by G05SDF from a χ^2 -distribution with ν degrees of freedom.

One of the initialization routines G05KFF (for a repeatable sequence if computed sequentially) or G05KGF (for a non-repeatable sequence) must be called prior to the first call to G05RYF.

4 References

Knuth D E (1981) *The Art of Computer Programming (Volume 2)* (2nd Edition) Addison-Wesley Wilkinson J H (1965) *The Algebraic Eigenvalue Problem* Oxford University Press, Oxford

5 Parameters

1: MODE – INTEGER Input

On entry: a code for selecting the operation to be performed by the routine.

MODE = 0

Set up reference vector only.

MODE = 1

Generate variates using reference vector set up in a prior call to G05RYF.

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MODE = 2

Set up reference vector and generate variates.

Constraint: MODE = 0, 1 or 2.

2: N – INTEGER Input

On entry: n, the number of random variates required.

Constraint: N > 0.

3: DF – INTEGER Input

On entry: ν , the number of degrees of freedom of the distribution.

Constraint: DF \geq 3.

4: M – INTEGER Input

On entry: m, the number of dimensions of the distribution.

Constraint: M > 0.

5: XMU(M) – REAL (KIND=nag wp) array

Input

On entry: a, the vector of means of the distribution.

6: C(LDC,M) - REAL (KIND=nag wp) array

Input

On entry: matrix which, along with DF, defines the covariance of the distribution. Only the upper triangle need be set.

Constraint: C must be positive semidefinite to machine precision.

7: LDC – INTEGER Input

On entry: the first dimension of the array C as declared in the (sub)program from which G05RYF is called.

Constraint: LDC \geq M.

8: R(LR) – REAL (KIND=nag wp) array

Input/Output

On entry: if MODE = 1, the reference vector as set up by G05RYF in a previous call with MODE = 0 or 2.

On exit: if MODE = 0 or 2, the reference vector that can be used in subsequent calls to G05RYF with MODE = 1.

9: LR – INTEGER Input

On entry: the dimension of the array R as declared in the (sub)program from which G05RYF is called. If MODE = 1, it must be the same as the value of LR specified in the prior call to G05RYF with MODE = 0 or 2.

Constraint: LR \geq M \times (M + 1) + 2.

10: STATE(*) - INTEGER array

Communication Array

Note: the actual argument supplied must be the array STATE supplied to the initialization routines G05KFF or G05KGF.

On entry: contains information on the selected base generator and its current state.

On exit: contains updated information on the state of the generator.

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11: X(LDX,M) - REAL (KIND=nag wp) array

Output

Input

On exit: the array of pseudorandom multivariate Student's t vectors generated by the routine, with X(i,j) holding the jth dimension for the ith variate.

12: LDX – INTEGER

On entry: the first dimension of the array X as declared in the (sub)program from which G05RYF is called.

Constraint: $LDX \ge N$.

13: IFAIL – INTEGER

Input/Output

On entry: IFAIL must be set to 0, -1 or 1. If you are unfamiliar with this parameter you should refer to Section 3.3 in the Essential Introduction for details.

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, if you are not familiar with this parameter, the recommended value is 0. When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.

On exit: IFAIL = 0 unless the routine detects an error or a warning has been flagged (see Section 6).

6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

IFAIL = 1

On entry, MODE \neq 0, 1 or 2.

IFAIL = 2

On entry, N < 0.

IFAIL = 3

On entry, DF ≤ 2 .

IFAIL = 4

On entry, M < 1.

IFAIL = 6

The covariance matrix C is not positive semidefinite to *machine precision*.

IFAIL = 7

On entry, LDC < M.

IFAIL = 8

The reference vector R has been corrupted or M has changed since R was set up in a previous call to G05RYF with MODE = 0 or 2.

IFAIL = 9

On entry, $LR \leq M \times (M+1) + 1$.

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```
IFAIL = 10
```

On entry, STATE vector was not initialized or has been corrupted.

IFAIL = 12

On entry, LDX < N.

7 Accuracy

Not applicable.

8 Further Comments

The time taken by G05RYF is of order nm^3 .

It is recommended that the diagonal elements of C should not differ too widely in order of magnitude. This may be achieved by scaling the variables if necessary. The actual matrix decomposed is $C+E=LL^{\rm T}$, where E is a diagonal matrix with small positive diagonal elements. This ensures that, even when C is singular, or nearly singular, the Cholesky factor L corresponds to a positive definite covariance matrix that agrees with C within *machine precision*.

9 Example

This example prints ten pseudorandom observations from a multivariate Student's t-distribution with ten degrees of freedom, means vector

$$\begin{bmatrix}
1.0 \\
2.0 \\
-3.0 \\
0.0
\end{bmatrix}$$

and C matrix

$$\begin{bmatrix} 1.69 & 0.39 & -1.86 & 0.07 \\ 0.39 & 98.01 & -7.07 & -0.71 \\ -1.86 & -7.07 & 11.56 & 0.03 \\ 0.07 & -0.71 & 0.03 & 0.01 \end{bmatrix}$$

generated by G05RYF. All ten observations are generated by a single call to G05RYF with MODE = 2. The random number generator is initialized by G05KFF.

9.1 Program Text

```
Program g05ryfe
     GO5RYF Example Program Text
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!
      .. Use Statements ..
     Use nag_library, Only: g05kff, g05ryf, nag_wp, x04caf
      .. Implicit None Statement ..
!
     Implicit None
      .. Parameters ..
!
      Integer, Parameter
                                        :: lseed = 1, nin = 5, nout = 6
      .. Local Scalars ..
!
     Integer
                                        :: df, genid, i, ifail, ldc, ldx, lr,
                                           1state, m, mode, n, subid
      .. Local Arrays ..
     Real (Kind=nag_wp), Allocatable :: c(:,:), r(:), x(:,:), xmu(:)
                                       :: seed(lseed)
     Integer
     Integer, Allocatable
                                       :: state(:)
!
      .. Executable Statements ..
```

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```
Write (nout,*) 'G05RYF Example Program Results'
      Write (nout,*)
     Flush (nout)
     Skip heading in data file
     Read (nin,*)
     Read in the base generator information and seed
     Read (nin,*) genid, subid, seed(1)
     Initial call to initialiser to get size of STATE array
!
      lstate = 0
      Allocate (state(lstate))
      ifail = 0
      Call g05kff(genid, subid, seed, lseed, state, lstate, ifail)
     Reallocate STATE
     Deallocate (state)
     Allocate (state(lstate))
     Initialize the generator to a repeatable sequence
      ifail = 0
      Call g05kff(genid, subid, seed, lseed, state, lstate, ifail)
     Read in sample size and number of dimensions
     Read (nin,*) n, m
      ldc = m
      ldx = n
      1r = m*(m+1) + 2
      Allocate (x(ldx,m),c(ldc,m),r(lr),xmu(m))
     Read in degrees of freedom
     Read (nin,*) df
     Read in vector of means
     Read (nin,*) xmu(1:m)
     Read in upper triangle portion of the covariance matrix
      Do i = 1, m
       Read (nin,*) c(i,i:m)
     End Do
      Using a single call to GO5RYF, so set up reference vector
     and generate values in one go
     mode = 2
     Generate variates
      ifail = 0
      Call g05ryf(mode,n,df,m,xmu,c,ldc,r,lr,state,x,ldx,ifail)
     Display the variates
      ifail = 0
      Call x04caf('General',' ',n,m,x,ldx,'Variates',ifail)
    End Program g05ryfe
```

9.2 Program Data

```
G05RYF Example Program Data
1 1 1762543 :: GENID, SUBID, SEED(1)
10 4 :: N,M
10 :: DF
1.0 2.0 -3.0 0.0 :: XMU
1.69 0.39 -1.86 0.07
98.01 -7.07 -0.71
11.56 0.03
0.01 :: End of C (upper triangular part)
```

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9.3 Program Results

GO5RYF Example Program Results

Variates				
	1	2	3	4
1	1.4957	-15.6226	-3.8101	0.1294
2	-1.0827	-6.7473	0.6696	-0.0391
3	2.1369	6.3861	- 5.7413	0.0140
4	2.2481	-16.0417	-1.0982	0.1641
5	-0.2550	3.5166	-0.2541	-0.0592
6	0.9731	-4. 3553	-4.4181	0.0043
7	0.7098	-3.4281	1.1741	0.0586
8	1.8827	23.2619	1.5140	-0.0704
9	0.9904	22.7479	0.1811	-0.0893
10	1.5026	2.7753	-2.2805	-0.0112

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