# NAG Library Routine Document

# F11MHF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of *bold italicised* terms and other implementation-dependent details.

#### 1 Purpose

F11MHF returns error bounds for the solution of a real sparse system of linear equations with multiple right-hand sides, AX = B or  $A^{T}X = B$ . It improves the solution by iterative refinement in standard precision, in order to reduce the backward error as much as possible.

## 2 Specification

```
SUBROUTINE F11MHF (TRANS, N, ICOLZP, IROWIX, A, IPRM, IL, LVAL, IU, & UVAL, NRHS, B, LDB, X, LDX, FERR, BERR, IFAIL)
```

N, ICOLZP(*), IROWIX(*), IPRM(7*N), IL(*), IU(*),	&
NRHS, LDB, LDX, IFAIL	
A(*), LVAL(*), UVAL(*), B(LDB,*), X(LDX,*),	&
FERR(NRHS), BERR(NRHS)	
TRANS	
	<pre>NRHS, LDB, LDX, IFAIL A(*), LVAL(*), UVAL(*), B(LDB,*), X(LDX,*), FERR(NRHS), BERR(NRHS)</pre>

## **3** Description

F11MHF returns the backward errors and estimated bounds on the forward errors for the solution of a real system of linear equations with multiple right-hand sides AX = B or  $A^{T}X = B$ . The routine handles each right-hand side vector (stored as a column of the matrix *B*) independently, so we describe the function of F11MHF in terms of a single right-hand side *b* and solution *x*.

Given a computed solution x, the routine computes the *component-wise backward error*  $\beta$ . This is the size of the smallest relative perturbation in each element of A and b such that if x is the exact solution of a perturbed system:

$$(A + \delta A)x = b + \delta b$$
  
then  $|\delta a_{ij}| \le \beta |a_{ij}|$  and  $|\delta b_i| \le \beta |b_i|$ .

Then the routine estimates a bound for the *component-wise forward error* in the computed solution, defined by:

$$\max_{i}|x_{i} - \hat{x}_{i}| / \max_{i}|x_{i}|$$

where  $\hat{x}$  is the true solution.

The routine uses the LU factorization  $P_rAP_c = LU$  computed by F11MEF and the solution computed by F11MFF.

## 4 References

Golub G H and Van Loan C F (1996) Matrix Computations (3rd Edition) Johns Hopkins University Press, Baltimore

#### 5 Parameters

1: TRANS – CHARACTER(1)

On entry: specifies whether AX = B or  $A^{T}X = B$  is solved.

TRANS = 'N' AX = B is solved. Input

TRANS = 'T'  $A^{T}X = B$  is solved.

Constraint: TRANS = 'N' or 'T'.

2: N – INTEGER

On entry: n, the order of the matrix A. Constraint:  $N \ge 0$ .

3: ICOLZP(\*) – INTEGER array

Note: the dimension of the array ICOLZP must be at least N + 1.

On entry: ICOLZP(i) contains the index in A of the start of a new column. See Section 2.1.3 in the F11 Chapter Introduction.

4: IROWIX(\*) – INTEGER array

Note: the dimension of the array IROWIX must be at least ICOLZP(N + 1) - 1, the number of nonzeros of the sparse matrix A.

On entry: the row index array of sparse matrix A.

5: A(\*) – REAL (KIND=nag\_wp) array

Note: the dimension of the array A must be at least ICOLZP(N + 1) - 1, the number of nonzeros of the sparse matrix A.

On entry: the array of nonzero values in the sparse matrix A.

6:  $IPRM(7 \times N) - INTEGER$  array

On entry: the column permutation which defines  $P_c$ , the row permutation which defines  $P_r$ , plus associated data structures as computed by F11MEF.

7: 
$$IL(*) - INTEGER$$
 array

**Note**: the dimension of the array IL must be at least as large as the dimension of the array of the same name in F11MEF.

On entry: records the sparsity pattern of matrix L as computed by F11MEF.

8: LVAL(\*) – REAL (KIND=nag\_wp) array

**Note**: the dimension of the array LVAL must be at least as large as the dimension of the array of the same name in F11MEF.

On entry: records the nonzero values of matrix L and some nonzero values of matrix U as computed by F11MEF.

9: IU(\*) – INTEGER array

**Note**: the dimension of the array IU must be at least as large as the dimension of the array of the same name in F11MEF.

On entry: records the sparsity pattern of matrix U as computed by F11MEF.

10: UVAL(\*) – REAL (KIND=nag\_wp) array

**Note**: the dimension of the array UVAL must be at least as large as the dimension of the array of the same name in F11MEF.

On entry: records some nonzero values of matrix U as computed by F11MEF.

Input

Input

Input

Input

Input

Input

Input

Input

Input

11:

NRHS – INTEGER On entry: nrhs, the number of right-hand sides in B. Constraint: NRHS  $\geq 0$ .

- B(LDB, \*) REAL (KIND=nag\_wp) array
  Note: the second dimension of the array B must be at least max(1, NRHS).
  On entry: the n by nrhs right-hand side matrix B.
- 13: LDB INTEGER

On entry: the first dimension of the array B as declared in the (sub)program from which F11MHF is called.

*Constraint*: LDB  $\geq \max(1, N)$ .

14: X(LDX, \*) – REAL (KIND=nag\_wp) array

Note: the second dimension of the array X must be at least max(1, NRHS).

On entry: the n by nrhs solution matrix X, as returned by F11MFF.

On exit: the n by nrhs improved solution matrix X.

15: LDX – INTEGER

On entry: the first dimension of the array X as declared in the (sub)program from which F11MHF is called.

*Constraint*:  $LDX \ge max(1, N)$ .

16: FERR(NRHS) – REAL (KIND=nag\_wp) array

On exit: FERR(j) contains an estimated error bound for the jth solution vector, that is, the jth column of X, for j = 1, 2, ..., nrhs.

17: BERR(NRHS) – REAL (KIND=nag\_wp) array

On exit: BERR(j) contains the component-wise backward error bound  $\beta$  for the *j*th solution vector, that is, the *j*th column of X, for j = 1, 2, ..., nrhs.

18: IFAIL – INTEGER

On entry: IFAIL must be set to 0, -1 or 1. If you are unfamiliar with this parameter you should refer to Section 3.3 in the Essential Introduction for details.

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, if you are not familiar with this parameter, the recommended value is 0. When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.

On exit: IFAIL = 0 unless the routine detects an error or a warning has been flagged (see Section 6).

Input

Input

Input

Input

Output

Output

Input/Output

## 6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

```
IFAIL = 1
```

 $\begin{array}{lll} & \text{On entry, } \text{TRANS} \neq '\text{N' or 'T',} \\ & \text{or} & \text{N} < 0, \\ & \text{or} & \text{NRHS} < 0, \\ & \text{or} & \text{LDB} < \max(1,\text{N}), \\ & \text{or} & \text{LDX} < \max(1,\text{N}). \end{array} \end{array}$ 

IFAIL = 2

Ill-defined row permutation in array IPRM. Internal checks have revealed that the IPRM array is corrupted.

IFAIL = 3

Ill-defined column permutations in array IPRM. Internal checks have revealed that the IPRM array is corrupted.

IFAIL = 301

Unable to allocate required internal workspace.

IFAIL = -99

An unexpected error has been triggered by this routine. Please contact NAG.

See Section 3.8 in the Essential Introduction for further information.

IFAIL = -399

Your licence key may have expired or may not have been installed correctly.

See Section 3.7 in the Essential Introduction for further information.

IFAIL = -999

Dynamic memory allocation failed.

See Section 3.6 in the Essential Introduction for further information.

## 7 Accuracy

The bounds returned in FERR are not rigorous, because they are estimated, not computed exactly; but in practice they almost always overestimate the actual error.

## 8 Parallelism and Performance

F11MHF is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

F11MHF makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the X06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this routine. Please also consult the Users' Note for your implementation for any additional implementation-specific information.

#### **9** Further Comments

At most five steps of iterative refinement are performed, but usually only one or two steps are required.

Estimating the forward error involves solving a number of systems of linear equations of the form Ax = b or  $A^{T}x = b$ ;

### 10 Example

This example solves the system of equations AX = B using iterative refinement and to compute the forward and backward error bounds, where

	(2.00	1.00	0	0	0 \			/ 1.56	3.12	
	0	0	1.00		0			-0.25	-0.50	
A =	4.00	0	1.00	0 1.00	1.00	and	B =	3.60	7.20	
	0	0	0	1.00	2.00			1.33	2.66	
	\ 0	-2.00	0	0	3.00/			0.52	$\begin{array}{c} 3.12 \\ -0.50 \\ 7.20 \\ 2.66 \\ 1.04 \end{array}$	

Here A is nonsymmetric and must first be factorized by F11MEF.

#### 10.1 Program Text

Program fllmhfe

```
1
     F11MHF Example Program Text
!
     Mark 25 Release. NAG Copyright 2014.
1
      .. Use Statements ..
     Use nag_library, Only: fllmdf, fllmef, fllmff, fllmhf, nag_wp, x04caf,
                                                                                &
                             x04cbf
1
      .. Implicit None Statement ..
     Implicit None
      .. Parameters ..
1
     Real (Kind=nag_wp), Parameter :: one = 1.E0_nag_wp
                                       :: nin = 5, nout = 6
     Integer, Parameter
1
      .. Local Scalars ..
     Real (Kind=nag_wp)
                                       :: flop, thresh
                                        :: i, ifail, j, ldb, ldx, n, nnz, nnzl, &
     Integer
                                          nnzu, nrhs, nzlmx, nzlumx, nzumx
     Character (1)
                                       :: spec, trans
!
      .. Local Arrays ..
     Real (Kind=nag_wp), Allocatable :: a(:), b(:,:), berr(:), ferr(:),
                                                                                &
                                           lval(:), uval(:), x(:,:)
     Integer, Allocatable
                                       :: icolzp(:), il(:), iprm(:),
                                                                                 &
                                          irowix(:), iu(:)
     Character (1)
                                       :: clabs(1), rlabs(1)
      .. Executable Statements ..
1
     Write (nout, *) 'F11MHF Example Program Results'
     Flush (nout)
     Skip heading in data file
1
     Read (nin,*)
1
     Read order of matrix and number of right hand sides
     Read (nin,*) n, nrhs
      ldb = n
      ldx = n
     Allocate (b(ldb,nrhs),berr(nrhs),ferr(nrhs),x(ldx,nrhs),icolzp(n+1), &
        iprm(7*n))
!
     Read the matrix A
     Read (nin,*) icolzp(1:n+1)
      nnz = icolzp(n+1) - 1
      Allocate (a(nnz),lval(8*nnz),uval(8*nnz),il(7*n+8*nnz+4),irowix(nnz), &
```

```
iu(2*n+8*nnz+1))
     Do i = 1, nnz
       Read (nin,*) a(i), irowix(i)
     End Do
1
     Read the right hand sides
     Do j = 1, nrhs
       Read (nin,*) x(1:n,j)
       b(1:n,j) = x(1:n,j)
     End Do
1
     Calculate COLAMD permutation
     spec = 'M'
     ifail: behaviour on error exit
1
             =0 for hard exit, =1 for quiet-soft, =-1 for noisy-soft
1
     ifail = 0
     Call f11mdf(spec,n,icolzp,irowix,iprm,ifail)
!
     Factorise
     thresh = one
     ifail = 0
     nzlmx = 8*nnz
     nzlumx = 8*nnz
     nzumx = 8*nnz
     Call fllmef(n,irowix,a,iprm,thresh,nzlmx,nzlumx,nzumx,il,lval,iu,uval, &
       nnzl,nnzu,flop,ifail)
     Compute solution in array X
1
     trans = 'N'
     ifail = 0
     Call f11mff(trans,n,iprm,il,lval,iu,uval,nrhs,x,ldx,ifail)
     Improve solution, and compute backward errors and estimated
1
1
     bounds on the forward errors
     Call fllmhf(trans,n,icolzp,irowix,a,iprm,il,lval,iu,uval,nrhs,b,ldb,x, &
       ldx,ferr,berr,ifail)
     Print solution
1
     Write (nout,*)
     Flush (nout)
     Call x04cbf('G','X',nrhs,1,berr,nrhs,'1PE8.1','Backward Error','N', &
       rlabs,'N',clabs,80,0,ifail)
   End Program fllmhfe
```

#### 10.2 Program Data

```
F11MHF Example Program Data
   5 2 N, NRHS
   1
   3
   5
   7
   9
   12 ICOLZP(I) I=1,..,N+1
   2. 1
```

```
4.
       3
 1.
       1
       5
2
-2.
 1.
1.
       3
       2
-1.
1.
       4
 1.
       3
 2.
       4
3. 5 A(I), IROWIX(I) I=1,NNZ
1.56 -.25 3.6 1.33 .52
3.12 -.50 7.2 2.66 1.04 X(I,J) J=1,NRHS I=1,N
```

#### 10.3 Program Results

F11MHF Example Program Results

Solutions

1 2 0.7000 1 1.4000 2 0.1600 0.3200 3 0.5200 1.0400 1.5400 4 0.7700 5 0.2800 0.5600 Estimated Forward Error 5.0E-15 5.0E-15 Backward Error 3.6E-17 3.6E-17