

# NAG Library Function Document

## nag\_dgelsd (f08kcc)

### 1 Purpose

nag\_dgelsd (f08kcc) computes the minimum norm solution to a real linear least squares problem

$$\min_x \|b - Ax\|_2.$$

### 2 Specification

```
#include <nag.h>
#include <nagf08.h>

void nag_dgelsd (Nag_OrderType order, Integer m, Integer n, Integer nrhs,
                double a[], Integer pda, double b[], Integer pdb, double s[],
                double rcond, Integer *rank, NagError *fail)
```

### 3 Description

nag\_dgelsd (f08kcc) uses the singular value decomposition (SVD) of  $A$ , where  $A$  is a real  $m$  by  $n$  matrix which may be rank-deficient.

Several right-hand side vectors  $b$  and solution vectors  $x$  can be handled in a single call; they are stored as the columns of the  $m$  by  $r$  right-hand side matrix  $B$  and the  $n$  by  $r$  solution matrix  $X$ .

The problem is solved in three steps:

1. reduce the coefficient matrix  $A$  to bidiagonal form with Householder transformations, reducing the original problem into a ‘bidiagonal least squares problem’ (BLS);
2. solve the BLS using a divide-and-conquer approach;
3. apply back all the Householder transformations to solve the original least squares problem.

The effective rank of  $A$  is determined by treating as zero those singular values which are less than **rcond** times the largest singular value.

### 4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users’ Guide* (3rd Edition) SIAM, Philadelphia <http://www.netlib.org/lapack/lug>

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

### 5 Arguments

1: **order** – Nag\_OrderType *Input*

*On entry:* the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag\_RowMajor. See Section 3.2.1.3 in the Essential Introduction for a more detailed explanation of the use of this argument.

*Constraint:* **order** = Nag\_RowMajor or Nag\_ColMajor.

- 2: **m** – Integer *Input*  
*On entry:*  $m$ , the number of rows of the matrix  $A$ .  
*Constraint:*  $\mathbf{m} \geq 0$ .
- 3: **n** – Integer *Input*  
*On entry:*  $n$ , the number of columns of the matrix  $A$ .  
*Constraint:*  $\mathbf{n} \geq 0$ .
- 4: **nrhs** – Integer *Input*  
*On entry:*  $r$ , the number of right-hand sides, i.e., the number of columns of the matrices  $B$  and  $X$ .  
*Constraint:*  $\mathbf{nrhs} \geq 0$ .
- 5: **a**[*dim*] – double *Input/Output*  
**Note:** the dimension, *dim*, of the array **a** must be at least  
 $\max(1, \mathbf{pda} \times \mathbf{n})$  when **order** = Nag\_ColMajor;  
 $\max(1, \mathbf{m} \times \mathbf{pda})$  when **order** = Nag\_RowMajor.  
The ( $i, j$ )th element of the matrix  $A$  is stored in  
 $\mathbf{a}[(j-1) \times \mathbf{pda} + i - 1]$  when **order** = Nag\_ColMajor;  
 $\mathbf{a}[(i-1) \times \mathbf{pda} + j - 1]$  when **order** = Nag\_RowMajor.  
*On entry:* the  $m$  by  $n$  coefficient matrix  $A$ .  
*On exit:* the contents of **a** are destroyed.
- 6: **pda** – Integer *Input*  
*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **a**.  
*Constraints:*  
if **order** = Nag\_ColMajor,  $\mathbf{pda} \geq \max(1, \mathbf{m})$ ;  
if **order** = Nag\_RowMajor,  $\mathbf{pda} \geq \max(1, \mathbf{n})$ .
- 7: **b**[*dim*] – double *Input/Output*  
**Note:** the dimension, *dim*, of the array **b** must be at least  
 $\max(1, \mathbf{pdb} \times \mathbf{nrhs})$  when **order** = Nag\_ColMajor;  
 $\max(1, \max(1, \mathbf{m}, \mathbf{n}) \times \mathbf{pdb})$  when **order** = Nag\_RowMajor.  
The ( $i, j$ )th element of the matrix  $B$  is stored in  
 $\mathbf{b}[(j-1) \times \mathbf{pdb} + i - 1]$  when **order** = Nag\_ColMajor;  
 $\mathbf{b}[(i-1) \times \mathbf{pdb} + j - 1]$  when **order** = Nag\_RowMajor.  
*On entry:* the  $m$  by  $r$  right-hand side matrix  $B$ .  
*On exit:* **b** is overwritten by the  $n$  by  $r$  solution matrix  $X$ . If  $m \geq n$  and **rank** =  $n$ , the residual sum of squares for the solution in the  $i$ th column is given by the sum of squares of elements  $n + 1, \dots, m$  in that column.
- 8: **pdb** – Integer *Input*  
*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **b**.

Constraints:

if **order** = Nag\_ColMajor, **pdb**  $\geq$   $\max(1, \mathbf{m}, \mathbf{n})$ ;  
 if **order** = Nag\_RowMajor, **pdb**  $\geq$   $\max(1, \mathbf{nrhs})$ .

- 9: **s**[*dim*] – double Output  
**Note:** the dimension, *dim*, of the array **s** must be at least  $\max(1, \min(\mathbf{m}, \mathbf{n}))$ .  
*On exit:* the singular values of *A* in decreasing order.
- 10: **rcond** – double Input  
*On entry:* used to determine the effective rank of *A*. Singular values  $\mathbf{s}[i - 1] \leq \mathbf{rcond} \times \mathbf{s}[0]$  are treated as zero. If **rcond** < 0, *machine precision* is used instead.
- 11: **rank** – Integer \* Output  
*On exit:* the effective rank of *A*, i.e., the number of singular values which are greater than  $\mathbf{rcond} \times \mathbf{s}[0]$ .
- 12: **fail** – NagError \* Input/Output  
 The NAG error argument (see Section 3.6 in the Essential Introduction).

## 6 Error Indicators and Warnings

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.

### NE\_BAD\_PARAM

On entry, argument  $\langle value \rangle$  had an illegal value.

### NE\_CONVERGENCE

The algorithm for computing the SVD failed to converge;  $\langle value \rangle$  off-diagonal elements of an intermediate bidiagonal form did not converge to zero.

### NE\_INT

On entry, **m** =  $\langle value \rangle$ .  
 Constraint: **m**  $\geq$  0.

On entry, **n** =  $\langle value \rangle$ .  
 Constraint: **n**  $\geq$  0.

On entry, **nrhs** =  $\langle value \rangle$ .  
 Constraint: **nrhs**  $\geq$  0.

On entry, **pda** =  $\langle value \rangle$ .  
 Constraint: **pda** > 0.

On entry, **pdb** =  $\langle value \rangle$ .  
 Constraint: **pdb** > 0.

### NE\_INT\_2

On entry, **pda** =  $\langle value \rangle$  and **m** =  $\langle value \rangle$ .  
 Constraint: **pda**  $\geq$   $\max(1, \mathbf{m})$ .

On entry, **pda** =  $\langle value \rangle$  and **n** =  $\langle value \rangle$ .  
 Constraint: **pda**  $\geq$   $\max(1, \mathbf{n})$ .

On entry, **pdb** =  $\langle value \rangle$  and **nrhs** =  $\langle value \rangle$ .  
 Constraint: **pdb**  $\geq$  max(1, **nrhs**).

### NE\_INT\_3

On entry, **pdb** =  $\langle value \rangle$ , **m** =  $\langle value \rangle$  and **n** =  $\langle value \rangle$ .  
 Constraint: **pdb**  $\geq$  max(1, **m**, **n**).

### NE\_INTERNAL\_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

## 7 Accuracy

See Section 4.5 of Anderson *et al.* (1999) for details.

## 8 Parallelism and Performance

nag\_dgelsd (f08kcc) is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

nag\_dgelsd (f08kcc) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the Users' Note for your implementation for any additional implementation-specific information.

## 9 Further Comments

The complex analogue of this function is nag\_zgelsd (f08kqc).

## 10 Example

This example solves the linear least squares problem

$$\min_x \|b - Ax\|_2$$

for the solution,  $x$ , of minimum norm, where

$$A = \begin{pmatrix} -0.09 & -1.56 & -1.48 & -1.09 & 0.08 & -1.59 \\ 0.14 & 0.20 & -0.43 & 0.84 & 0.55 & -0.72 \\ -0.46 & 0.29 & 0.89 & 0.77 & -1.13 & 1.06 \\ 0.68 & 1.09 & -0.71 & 2.11 & 0.14 & 1.24 \\ 1.29 & 0.51 & -0.96 & -1.27 & 1.74 & 0.34 \end{pmatrix} \quad \text{and} \quad b = \begin{pmatrix} 7.4 \\ 4.3 \\ -8.1 \\ 1.8 \\ 8.7 \end{pmatrix}.$$

A tolerance of 0.01 is used to determine the effective rank of  $A$ .

### 10.1 Program Text

```
/* nag_dgelsd (f08kcc) Example Program.
 *
 * Copyright 2011 Numerical Algorithms Group.
 *
 * Mark 23, 2011.
 */

#include <stdio.h>
#include <nag.h>
#include <nagf08.h>
#include <nag_stdlib.h>
```

```

int main(void)
{
    /* Scalars */
    double      rcond;
    Integer     exit_status = 0, i, j, m, n, nrhs, rank, pda, pdb;

    /* Arrays */
    double      *a = 0, *b = 0, *s = 0;

    /* Nag Types */
    NagError    fail;
    Nag_OrderType order;

#ifdef NAG_COLUMN_MAJOR
#define A(I, J) a[(J - 1) * pda + I - 1]
#define B(I, J) b[(J - 1) * pdb + I - 1]
    order = Nag_ColMajor;
#else
#define A(I, J) a[(I - 1) * pda + J - 1]
#define B(I, J) b[(I - 1) * pdb + J - 1]
    order = Nag_RowMajor;
#endif

    INIT_FAIL(fail);

    printf("nag_dgelsd (f08kcc) Example Program Results\n\n");

    /* Skip heading in data file */
    scanf("%*[\n]");
    scanf("%ld%ld%ld%*[\n]", &m, &n, &nrhs);
    if (m < 0 || n < 0 || nrhs < 0)
    {
        printf("Invalid m, n or nrhs\n");
        exit_status = 1;
        goto END;
    }

    /* Allocate memory */
    if (!(a = NAG_ALLOC(m * n, double)) ||
        !(b = NAG_ALLOC(MAX(m, n) * nrhs, double)) ||
        !(s = NAG_ALLOC(MIN(m, n), double)))
    {
        printf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }

#ifdef NAG_COLUMN_MAJOR
    pda = m;
    pdb = MAX(m, n);
#else
    pda = n;
    pdb = nrhs;
#endif

    /* Read A and B from data file */
    for (i = 1; i <= m; ++i)
        for (j = 1; j <= n; ++j) scanf("%lf", &A(i, j));
    scanf("%*[\n]");

    for (i = 1; i <= m; ++i)
        for (j = 1; j <= nrhs; ++j) scanf("%lf", &B(i, j));
    scanf("%*[\n]");

    rcond = 0.01;
    nag_dgelsd(order, m, n, 1, a, pda, b, pdb, s, rcond, &rank, &fail);

    if (fail.code != NE_NOERROR)
    {
        printf("Error from nag_dgelsd (f08kcc).\n%s\n", fail.message);
    }
}

```

```

        exit_status = 1;
        goto END;
    }

    /* Print solution */
    printf("Least squares solution\n");
    for (i = 1; i <= n; ++i)
    {
        for (j = 1; j <= nrhs; ++j)
            printf(" %10.4f%s", B(i, j), j%7==0?"\n":""");
        printf("\n");
    }

    /* Print the effective rank of A */
    printf("\n\nTolerance used to estimate the rank of A\n%11.2e\n", rcond);
    printf("\nEstimated rank of A\n%6ld\n", rank);

    /* Print singular values of A */
    printf("\nSingular values of A\n");
    for (i = 0; i < m; ++i) printf(" %10.4f%s", s[i], i%7 == 6?"\n":""");
    printf("\n");

    END:
    NAG_FREE(a);
    NAG_FREE(b);
    NAG_FREE(s);

    return exit_status;
}
#undef A
#undef B

```

## 10.2 Program Data

nag\_dgelsd (f08kcc) Example Program Data

```

    5      6      1                               : m, n, nrhs
-0.09  -1.56  -1.48  -1.09   0.08  -1.59
 0.14   0.20  -0.43   0.84   0.55  -0.72
-0.46   0.29   0.89   0.77  -1.13   1.06
 0.68   1.09  -0.71   2.11   0.14   1.24
 1.29   0.51  -0.96  -1.27   1.74   0.34 : matrix A

 7.4
 4.3
-8.1
 1.8
 8.7                               : vector b

```

### 10.3 Program Results

nag\_dgelsd (f08kcc) Example Program Results

Least squares solution

1.5938  
-0.1180  
-3.1501  
0.1554  
2.5529  
-1.6730

Tolerance used to estimate the rank of A

1.00e-02

Estimated rank of A

4

Singular values of A

3.9997      2.9962      2.0001      0.9988      0.0025

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