

# NAG Library Function Document

## **nag\_superlu\_lu\_factorize (f11mec)**

### 1 Purpose

`nag_superlu_lu_factorize (f11mec)` computes the *LU* factorization of a real sparse matrix in compressed column (Harwell–Boeing), column-permuted format.

### 2 Specification

```
#include <nag.h>
#include <nagf11.h>
void nag_superlu_lu_factorize (Integer n, const Integer irowix[],
                               const double a[], Integer iprm[], double thresh, Integer nzlmx,
                               Integer *nzlumx, Integer nzumx, Integer il[], double lval[],
                               Integer iu[], double uval[], Integer *nnzl, Integer *nnzu, double *flop,
                               NagError *fail)
```

### 3 Description

Given a real sparse matrix  $A$ , `nag_superlu_lu_factorize (f11mec)` computes an *LU* factorization of  $A$  with partial pivoting,  $P_r A P_c = LU$ , where  $P_r$  is a row permutation matrix (computed by `nag_superlu_lu_factorize (f11mec)`),  $P_c$  is a (supplied) column permutation matrix,  $L$  is unit lower triangular and  $U$  is upper triangular. The column permutation matrix,  $P_c$ , must be computed by a prior call to `nag_superlu_column_permutation (f11mdc)`. The matrix  $A$  must be presented in the column permuted, compressed column (Harwell–Boeing) format.

The *LU* factorization is output in the form of four one-dimensional arrays: integer arrays **il** and **iu** and real-valued arrays **lval** and **uval**. These describe the sparsity pattern and numerical values in the  $L$  and  $U$  matrices. The minimum required dimensions of these arrays cannot be given as a simple function of the size arguments (order and number of nonzero values) of the matrix  $A$ . This is due to unpredictable fill-in created by partial pivoting. `nag_superlu_lu_factorize (f11mec)` will, on return, indicate which dimensions of these arrays were not adequate for the computation or (in the case of one of them) give a firm bound. You should then allocate more storage and try again.

### 4 References

Demmel J W, Eisenstat S C, Gilbert J R, Li X S and Li J W H (1999) A supernodal approach to sparse partial pivoting *SIAM J. Matrix Anal. Appl.* **20** 720–755

Demmel J W, Gilbert J R and Li X S (1999) An asynchronous parallel supernodal algorithm for sparse gaussian elimination *SIAM J. Matrix Anal. Appl.* **20** 915–952

### 5 Arguments

1: **n** – Integer *Input*

*On entry:*  $n$ , the order of the matrix  $A$ .

*Constraint:*  $\mathbf{n} \geq 0$ .

2: **irowix[dim]** – const Integer *Input*

**Note:** the dimension,  $dim$ , of the array **irowix** must be at least  $nnz$ , the number of nonzeros of the sparse matrix  $A$ .

*On entry:* the row index array of sparse matrix  $A$ .

3: **a**[*dim*] – const double *Input*

**Note:** the dimension,  $\dim$ , of the array  $\mathbf{a}$  must be at least  $nnz$ , the number of nonzeros of the sparse matrix  $A$ .

*On entry:* the array of nonzero values in the sparse matrix  $A$ .

4: **iprm[7 × n]** – Integer *Input/Output*

*On entry:* contains the column permutation which defines the permutation  $P_c$  and associated data structures as computed by function nag\_superlu\_column\_permutation (f11mdc).

*On exit:* part of the array is modified to record the row permutation  $P_r$  determined by pivoting.

On entry: the diagonal pivoting threshold,  $t$ . At step  $j$  of the Gaussian elimination, if  $|A_{jj}| \geq t \left( \max_{i \geq j} |A_{ij}| \right)$ , use  $A_{jj}$  as a pivot, otherwise use  $\max_{i \geq j} |A_{ij}|$ . A value of  $t = 1$  corresponds to partial pivoting, a value of  $t = 0$  corresponds to always choosing the pivot on the diagonal (unless it is zero).

*Suggested value:* `thresh` = 1.0. Smaller values may result in a faster factorization, but the benefits are likely to be small in most cases. It might be possible to use `thresh` = 0.0 if you are confident about the stability of the factorization, for example, if  $A$  is diagonally dominant.

*Constraint:*  $0.0 \leq \text{thresh} \leq 1.0$ .

6: **nzlmx** – Integer *Input*

*On entry:* indicates the available size of array **il**. The dimension of **il** should be at least  $7 \times \mathbf{n} + \mathbf{nzlmx} + 4$ . A good range for **nzlmx** that works for many problems is  $nnz$  to  $8 \times nnz$ , where  $nnz$  is the number of nonzeros in the sparse matrix  $A$ . If, on exit, **fail.code** = **NE\_NZLMX\_TOO\_SMALL**, the given **nzlmx** was too small and you should attempt to provide more storage and call the function again.

*Constraint:* **nzlmx**  $\geq 1$ .

7: **nzlumx** – Integer \*

*On entry:* indicates the available size of array **lval**. The dimension of **lval** should be at least **nzlmx**.

*Constraint:* **nzlumx**  $\geq 1$ .

*On exit:* if **fail.code** = **NE\_NZLUMX\_TOO\_SMALL**, the given **nzlumx** was too small and is reset to a value that will be sufficient. You should then provide the indicated storage and call the function again.

8: **nzumx** – Integer *Input*

**On entry:** indicates the available sizes of arrays **iu** and **uval**. The dimension of **iu** should be at least  $2 \times \mathbf{n} + \mathbf{nzumx} + 1$  and the dimension of **uval** should be at least **nzumx**. A good range for **nzumx** that works for many problems is  $nnz$  to  $8 \times nnz$ , where  $nnz$  is the number of nonzeros in the sparse matrix  $A$ . If, on exit, **fail.code** = **NE\_NZUMX\_TOO\_SMALL**, the given **nzumx** was too small and you should attempt to provide more storage and call the function again.

*Constraint:*  $\text{nzumx} \geq 1$ .

*On exit:* encapsulates the sparsity pattern of matrix  $L$ .

10: **lval[nzlumx]** – double *Output*

*On exit:* records the nonzero values of matrix  $L$  and some of the nonzero values of matrix  $U$ .

11:	<b>iu</b> [ $2 \times \mathbf{n} + \mathbf{nzumx} + 1$ ] – Integer	<i>Output</i>
<i>On exit:</i> encapsulates the sparsity pattern of matrix $U$ .		
12:	<b>uval</b> [ $\mathbf{nzumx}$ ] – double	<i>Output</i>
<i>On exit:</i> records some of the nonzero values of matrix $U$ .		
13:	<b>nnzl</b> – Integer *	<i>Output</i>
<i>On exit:</i> the number of nonzero values in the matrix $L$ .		
14:	<b>nnzu</b> – Integer *	<i>Output</i>
<i>On exit:</i> the number of nonzero values in the matrix $U$ .		
15:	<b>flop</b> – double *	<i>Output</i>
<i>On exit:</i> the number of floating-point operations performed.		
16:	<b>fail</b> – NagError *	<i>Input/Output</i>
The NAG error argument (see Section 3.6 in the Essential Introduction).		

## 6 Error Indicators and Warnings

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.

### NE\_BAD\_PARAM

On entry, argument  $\langle\text{value}\rangle$  had an illegal value.

### NE\_INT

On entry,  $\mathbf{n} = \langle\text{value}\rangle$ .  
Constraint:  $\mathbf{n} \geq 0$ .

On entry,  $\mathbf{nzlmx} = \langle\text{value}\rangle$ .  
Constraint:  $\mathbf{nzlmx} \geq 1$ .

On entry,  $\mathbf{nzlumx} = \langle\text{value}\rangle$ .  
Constraint:  $\mathbf{nzlumx} \geq 1$ .

On entry,  $\mathbf{nzumx} = \langle\text{value}\rangle$ .  
Constraint:  $\mathbf{nzumx} \geq 1$ .

### NE\_INTERNAL\_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

### NE\_NZLMX\_TOO\_SMALL

Insufficient  $\mathbf{nzlmx}$ .

### NE\_NZLUMX\_TOO\_SMALL

Insufficient  $\mathbf{nzlumx}$ .

### NE\_NZUMX\_TOO\_SMALL

Insufficient  $\mathbf{nzumx}$ .

**NE\_REAL**

On entry, **thresh** =  $\langle value \rangle$ .  
 Constraint:  $0.0 \leq \text{thresh} \leq 1.0$ .

**NE\_SINGULAR\_MATRIX**

The matrix is singular – no factorization possible.

## 7 Accuracy

The computed factors  $L$  and  $U$  are the exact factors of a perturbed matrix  $A + E$ , where

$$|E| \leq c(n)\epsilon|L||U|,$$

$c(n)$  is a modest linear function of  $n$ , and  $\epsilon$  is the **machine precision**, when partial pivoting is used. If no partial pivoting is used, the factorization accuracy can be considerably worse. A call to nag\_superlu\_diagnostic\_lu (f11mmc) after nag\_superlu\_lu\_factorize (f11mec) can help determine the quality of the factorization.

## 8 Parallelism and Performance

nag\_superlu\_lu\_factorize (f11mec) is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

nag\_superlu\_lu\_factorize (f11mec) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the Users' Note for your implementation for any additional implementation-specific information.

## 9 Further Comments

The total number of floating-point operations depends on the sparsity pattern of the matrix  $A$ .

A call to nag\_superlu\_lu\_factorize (f11mec) may be followed by calls to the functions:

- nag\_superlu\_solve\_lu (f11mfc) to solve  $AX = B$  or  $A^T X = B$ ;
- nag\_superlu\_condition\_number\_lu (f11mgc) to estimate the condition number of  $A$ ;
- nag\_superlu\_diagnostic\_lu (f11mmc) to estimate the reciprocal pivot growth of the  $LU$  factorization.

## 10 Example

This example computes the  $LU$  factorization of the matrix  $A$ , where

$$A = \begin{pmatrix} 2.00 & 1.00 & 0 & 0 & 0 \\ 0 & 0 & 1.00 & -1.00 & 0 \\ 4.00 & 0 & 1.00 & 0 & 1.00 \\ 0 & 0 & 0 & 1.00 & 2.00 \\ 0 & -2.00 & 0 & 0 & 3.00 \end{pmatrix}.$$

### 10.1 Program Text

```
/* nag_superlu_lu_factorize (f11mec) Example Program.
 *
 * Copyright 2005 Numerical Algorithms Group.
 *
 * Mark 8, 2005.
 */
```

```

#include <stdio.h>
#include <nag.h>
#include <nagx04.h>
#include <nag_stdlib.h>
#include <nagf11.h>

/* Table of constant values */

int main(void)
{
    double                  flop, thresh;
    Integer                exit_status = 0, i, n, nnz, nnzl, nnzu, nzlmx,
                           nzlumx, nzumx;
    double                 *a = 0, *lval = 0, *uval = 0;
    Integer                *icolzp = 0, *il = 0, *iprm = 0, *irowix = 0;
    Integer                *iu = 0;
    /* Nag types */
    NagError               fail;
    Nag_ColumnPermutationType ispec;
    Nag_OrderType           order = Nag_ColMajor;
    Nag_MatrixType          matrix = Nag_GeneralMatrix;
    Nag_DiagType            diag = Nag_NonUnitDiag;

    INIT_FAIL(fail);

    /* nag_superlu_lu_factorize (f11mec).
     * LU factorization of real sparse matrix
     */
    printf(
        "nag_superlu_lu_factorize (f11mec) Example Program Results\n\n");
    /* Skip heading in data file */
    scanf("%*[^\n] ");
    /* Read order of matrix */
    scanf("%ld%*[^\n] ", &n);
    /* Read the matrix A */
    /* Allocate memory */
    if (!(icolzp = NAG_ALLOC(n+1, Integer)))
    {
        printf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }
    for (i = 1; i <= n+1; ++i) scanf("%ld%*[^\n] ", &icolzp[i - 1]);
    nnz = icolzp[n] - 1;
    /* Allocate memory */
    if (!(irowix = NAG_ALLOC(nnz, Integer)) ||
        !(a = NAG_ALLOC(nnz, double)) ||
        !(il = NAG_ALLOC(7*n+8*nnz+4, Integer)) ||
        !(iu = NAG_ALLOC(2*n+8*nnz+1, Integer)) ||
        !(uval = NAG_ALLOC(8*nnz, double)) ||
        !(lval = NAG_ALLOC(8*nnz, double)) ||
        !(iprm = NAG_ALLOC(7*n, Integer)))
    {
        printf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }
    for (i = 1; i <= nnz; ++i)
        scanf("%lf%ld%*[^\n] ", &a[i - 1], &irowix[i - 1]);
    /* Calculate COLAMD permutation */
    ispec = Nag_Sparse_Colamd;
    /* nag_superlu_column_permutation (f11mdc).
     * Real sparse nonsymmetric linear systems, setup for
     * nag_superlu_lu_factorize (f11mec)
     */
    nag_superlu_column_permutation(ispec, n, icolzp, irowix, iprm, &fail);
    if (fail.code != NE_NOERROR)
    {
        printf(
            "Error from nag_superlu_column_permutation (f11mdc).\n%s\n",

```

```

        fail.message);
    exit_status = 1;
    goto END;
}
/* Factorise */
thresh = 1.;
nzlmx = 8*nnz;
nzlumx = 8*nnz;
nzumx = 8*nnz;
/* nag_superlu_lu_factorize (f11mec), see above. */
nag_superlu_lu_factorize(n, irowix, a, iprm, thresh, nzlmx, &nzlumx, nzumx,
                           il, lval, iu, uval, &nnzl, &nnzu, &flop, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_superlu_lu_factorize (f11mec).\\n%s\\n",
           fail.message);
    exit_status = 1;
    goto END;
}

/* Output results */
printf("\n");
printf("Number of nonzeros in factors (excluding unit diagonal)\\n");
printf("%8ld\\n\\n", nnzl + nnzu - n);
/* nag_gen_real_mat_print_comp (x04cbc).
 * Print real general matrix (comprehensive)
 */
fflush(stdout);
nag_gen_real_mat_print_comp(order, matrix, diag, 1, 10, lval, 1, "%6.2f",
                            "Factor elements in LVAL", Nag_NoLabels, NULL,
                            Nag_NoLabels, NULL, 80, 1, 0, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_gen_real_mat_print_comp (x04cbc).\\n%s\\n",
           fail.message);
    exit_status = 1;
    goto END;
}

printf("\n");
/* nag_gen_real_mat_print_comp (x04cbc), see above. */
fflush(stdout);
nag_gen_real_mat_print_comp(order, matrix, diag, 1, 4, uval, 1, "%6.2f",
                            "Factor elements in LVAL", Nag_NoLabels, NULL,
                            Nag_NoLabels, NULL, 80, 1, 0, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_gen_real_mat_print_comp (x04cbc).\\n%s\\n",
           fail.message);
    exit_status = 1;
    goto END;
}

END:
NAG_FREE(a);
NAG_FREE(lval);
NAG_FREE(uval);
NAG_FREE(icolzp);
NAG_FREE(il);
NAG_FREE(iprm);
NAG_FREE(irowix);
NAG_FREE(iu);

return exit_status;
}

```

## 10.2 Program Data

```
nag_superlu_lu_factorize (f11mec) Example Program Data
      5          n
      1
      3
      5
      7
      9
12   icolzp(i) i=0..n
  2.    1
  4.    3
  1.    1
-2.    5
  1.    2
  1.    3
-1.    2
  1.    4
  1.    3
  2.    4
  3.    5      a(i), irowix(i) i=0..nnz-1
```

## 10.3 Program Results

```
nag_superlu_lu_factorize (f11mec) Example Program Results
```

Number of nonzeros in factors (excluding unit diagonal)  
14

Factor elements in LVAL
-2.00 -0.50 4.00 0.50 2.00 0.50 -1.00 0.50 1.00 -1.00

Factor elements in LVAL
1.00 3.00 1.00 1.00

---