NAG Library Function Document

nag_1d_cheb_deriv (e02ahc)

1 Purpose

nag_1d_cheb_deriv (e02ahc) determines the coefficients in the Chebyshev series representation of the derivative of a polynomial given in Chebyshev series form.

2 Specification

3 Description

nag_1d_cheb_deriv (e02ahc) forms the polynomial which is the derivative of a given polynomial. Both the original polynomial and its derivative are represented in Chebyshev series form. Given the coefficients a_i , for i = 0, 1, ..., n, of a polynomial p(x) of degree n, where

$$p(x) = \frac{1}{2}a_0 + a_1T_1(\bar{x}) + \dots + a_nT_n(\bar{x})$$

the function returns the coefficients \bar{a}_i , for i = 0, 1, ..., n - 1, of the polynomial q(x) of degree n - 1, where

$$q(x) = \frac{dp(x)}{dx} = \frac{1}{2}\bar{a}_0 + \bar{a}_1T_1(\bar{x}) + \dots + \bar{a}_{n-1}T_{n-1}(\bar{x}).$$

Here $T_j(\bar{x})$ denotes the Chebyshev polynomial of the first kind of degree j with argument \bar{x} . It is assumed that the normalized variable \bar{x} in the interval [-1, +1] was obtained from your original variable x in the interval $[x_{\min}, x_{\max}]$ by the linear transformation

$$\bar{x} = \frac{2x - (x_{\max} + x_{\min})}{x_{\max} - x_{\min}}$$

and that you require the derivative to be with respect to the variable x. If the derivative with respect to \bar{x} is required, set $x_{\text{max}} = 1$ and $x_{\text{min}} = -1$.

Values of the derivative can subsequently be computed, from the coefficients obtained, by using nag_1d_cheb_eval2 (e02akc).

The method employed is that of Chebyshev series (see Chapter 8 of Modern Computing Methods (1961)), modified to obtain the derivative with respect to x. Initially setting $\bar{a}_{n+1} = \bar{a}_n = 0$, the function forms successively

$$\bar{a}_{i-1} = \bar{a}_{i+1} + \frac{2}{x_{\max} - x_{\min}} 2ia_i, \quad i = n, n-1, \dots, 1.$$

4 References

Modern Computing Methods (1961) Chebyshev-series NPL Notes on Applied Science 16 (2nd Edition) HMSO

5 Arguments

1: n – Integer

On entry: n, the degree of the given polynomial p(x).

Constraint: $\mathbf{n} > 0$.

- xmin double 2:
- xmax double 3:

On entry: the lower and upper end points respectively of the interval $[x_{\min}, x_{\max}]$. The Chebyshev series representation is in terms of the normalized variable \bar{x} , where

$$\bar{x} = \frac{2x - (x_{\max} + x_{\min})}{x_{\max} - x_{\min}}.$$

Constraint: **xmax** > **xmin**.

4: $\mathbf{a}[dim] - \text{const double}$

Note: the dimension, dim, of the array **a** must be at least $(1 + (\mathbf{n} + 1 - 1) \times i\mathbf{a}\mathbf{1})$.

On entry: the Chebyshev coefficients of the polynomial p(x). Specifically, element $i \times ia1$ of a must contain the coefficient a_i , for i = 0, 1, ..., n. Only these n + 1 elements will be accessed.

5: ia1 – Integer

> On entry: the index increment of a. Most frequently the Chebyshev coefficients are stored in adjacent elements of a, and ia1 must be set to 1. However, if for example, they are stored in $\mathbf{a}[0], \mathbf{a}[3], \mathbf{a}[6], \ldots$, then the value of **ia1** must be 3. See also Section 9.

Constraint: ial ≥ 1 .

patm1 - double * 6:

On exit: the value of $p(x_{\min})$. If this value is passed to the integration function nag 1d cheb intg (e02ajc) with the coefficients of q(x), then the original polynomial p(x) is recovered, including its constant coefficient.

adif[dim] – double 7:

Note: the dimension, dim, of the array adif must be at least $(1 + (n + 1 - 1) \times iadif1)$.

On exit: the Chebyshev coefficients of the derived polynomial q(x). (The differentiation is with respect to the variable x.) Specifically, element $i \times iadif1$ of adif contains the coefficient \bar{a}_i , for $i = 0, 1, \ldots, n - 1$. Additionally, element $n \times iadif1$ is set to zero.

8: iadif1 - Integer

On entry: the index increment of **adif**. Most frequently the Chebyshev coefficients are required in adjacent elements of adif, and iadif1 must be set to 1. However, if, for example, they are to be stored in **adif**[0], **adif**[3], **adif**[6],..., then the value of **iadif1** must be 3. See Section 9.

Constraint: iadif1 \geq 1.

fail - NagError * 9:

The NAG error argument (see Section 2.7 in How to Use the NAG Library and its Documentation).

Input

Output

Output

Input/Output

Input

Input

Input

Input

6 Error Indicators and Warnings

NE_ALLOC_FAIL

Dynamic memory allocation failed.

See Section 2.3.1.2 in How to Use the NAG Library and its Documentation for further information.

NE_BAD_PARAM

On entry, argument $\langle value \rangle$ had an illegal value.

NE_INT

On entry, $ia1 = \langle value \rangle$. Constraint: $ia1 \ge 1$.

On entry, **iadif1** = $\langle value \rangle$. Constraint: **iadif1** \geq 1.

On entry, $\mathbf{n} + 1 = \langle value \rangle$. Constraint: $\mathbf{n} + 1 \ge 1$.

On entry, $\mathbf{n} = \langle value \rangle$. Constraint: $\mathbf{n} \ge 0$.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

An unexpected error has been triggered by this function. Please contact NAG. See Section 2.7.6 in How to Use the NAG Library and its Documentation for further information.

NE_NO_LICENCE

Your licence key may have expired or may not have been installed correctly. See Section 2.7.5 in How to Use the NAG Library and its Documentation for further information.

NE_REAL_2

On entry, $\mathbf{xmax} = \langle value \rangle$ and $\mathbf{xmin} = \langle value \rangle$. Constraint: $\mathbf{xmax} > \mathbf{xmin}$.

7 Accuracy

There is always a loss of precision in numerical differentiation, in this case associated with the multiplication by 2i in the formula quoted in Section 3.

8 Parallelism and Performance

nag_1d_cheb_deriv (e02ahc) is not threaded in any implementation.

9 Further Comments

The time taken is approximately proportional to n + 1.

The increments **ia1**, **iadif1** are included as arguments to give a degree of flexibility which, for example, allows a polynomial in two variables to be differentiated with respect to either variable without rearranging the coefficients.

10 Example

Suppose a polynomial has been computed in Chebyshev series form to fit data over the interval [-0.5, 2.5]. The following program evaluates the first and second derivatives of this polynomial at 4 equally spaced points over the interval. (For the purposes of this example, **xmin**, **xmax** and the Chebyshev coefficients are simply supplied. Normally a program would first read in or generate data and compute the fitted polynomial.)

10.1 Program Text

```
/* nag_1d_cheb_deriv (e02ahc) Example Program.
* NAGPRODCODE Version.
*
* Copyright 2016 Numerical Algorithms Group.
* Mark 26, 2016.
 */
#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nage02.h>
int main(void)
{
  /* Initialized data */
 const double xmin = -0.5;
 const double xmax = 2.5;
 const double a[7] =
         { 2.53213, 1.13032, 0.2715, 0.04434, 0.00547, 5.4e-4, 4e-5 };
  /* Scalars */
 double deriv, deriv2, patm1, x;
 Integer exit_status, i, m, n, one;
 NagError fail;
  /* Arrays */
  double *adif = 0, *adif2 = 0;
 INIT_FAIL(fail);
 exit_status = 0;
 printf("nag_1d_cheb_deriv (e02ahc) Example Program Results\n");
 n = 6;
 one = 1;
  /* Allocate memory */
  if (!(adif = NAG_ALLOC(n + 1, double)) ||
      !(adif2 = NAG_ALLOC(n + 1, double)))
  {
   printf("Allocation failure\n");
   exit_status = -1;
    goto END;
 }
  /* nag_ld_cheb_deriv (e02ahc).
   * Derivative of fitted polynomial in Chebyshev series form
   */
 naq ld cheb deriv(n, xmin, xmax, a, one, &patml, adif, one, &fail);
  if (fail.code != NE_NOERROR) {
   printf("Error from nag_ld_cheb_deriv (e02ahc) call 1.\n%s\n",
           fail.message);
   exit_status = 1;
    goto END;
 }
  /* nag_ld_cheb_deriv (e02ahc), see above. */
```

```
nag_ld_cheb_deriv(n, xmin, xmax, adif, one, &patm1, adif2, one, &fail);
  if (fail.code != NE_NOERROR) {
   printf("Error from nag_ld_cheb_deriv (e02ahc) call 2.\n%s\n",
          fail.message);
    exit_status = 1;
   goto END;
  }
  m = 4;
  printf("\n");
  printf(" i Argument
                           1st deriv 2nd deriv\n");
  for (i = 1; i <= m; ++i) {
   x = (xmin * (double) (m - i) + xmax * (double) (i - 1)) / (double) (m - i)
                                                                        1);
    /* nag_1d_cheb_eval2 (e02akc).
    * Evaluation of fitted polynomial in one variable from
     * Chebyshev series form
    */
    nag_ld_cheb_eval2(n, xmin, xmax, adif, one, x, &deriv, &fail);
    if (fail.code != NE_NOERROR) {
     printf("Error from naq_1d_cheb_eval2 (e02akc) call 1.\n%s\n",
            fail.message);
     exit_status = 1;
     goto END;
    }
    /* nag_1d_cheb_eval2 (e02akc), see above. */
   nag_1d_cheb_eval2(n, xmin, xmax, adif2, one, x, &deriv2, &fail);
    if (fail.code != NE_NOERROR) {
     printf("Error from nag_1d_cheb_eval2 (e02akc) call 2.\n%s\n",
            fail.message);
     exit_status = 1;
     goto END;
    }
   printf("%4" NAG_IFMT "%9.4f %9.4f %9.4f \n", i, x, deriv,
           deriv2);
  }
END:
  NAG_FREE(adif);
 NAG_FREE(adif2);
 return exit_status;
```

10.2 Program Data

None.

}

10.3 Program Results

nag_ld_cheb_deriv (e02ahc) Example Program Results

i	Argument	1st deriv	2nd deriv
1	-0.5000	0.2453	0.1637
2	0.5000	0.4777	0.3185
3	1.5000	0.9304	0.6203
4	2.5000	1.8119	1.2056

