

NAG Library Routine Document

S17AGF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of *bold italicised* terms and other implementation-dependent details.

1 Purpose

S17AGF returns a value for the Airy function, $\text{Ai}(x)$, via the function name.

2 Specification

```
FUNCTION S17AGF (X, IFAIL)
REAL (KIND=nag_wp) S17AGF
INTEGER IFAIL
REAL (KIND=nag_wp) X
```

3 Description

S17AGF evaluates an approximation to the Airy function, $\text{Ai}(x)$. It is based on a number of Chebyshev expansions:

For $x < -5$,

$$\text{Ai}(x) = \frac{a(t) \sin z - b(t) \cos z}{(-x)^{1/4}}$$

where $z = \frac{\pi}{4} + \frac{2}{3}\sqrt{-x^3}$, and $a(t)$ and $b(t)$ are expansions in the variable $t = -2\left(\frac{5}{x}\right)^3 - 1$.

For $-5 \leq x \leq 0$,

$$\text{Ai}(x) = f(t) - xg(t),$$

where f and g are expansions in $t = -2\left(\frac{x}{5}\right)^3 - 1$.

For $0 < x < 4.5$,

$$\text{Ai}(x) = e^{-3x/2}y(t),$$

where y is an expansion in $t = 4x/9 - 1$.

For $4.5 \leq x < 9$,

$$\text{Ai}(x) = e^{-5x/2}u(t),$$

where u is an expansion in $t = 4x/9 - 3$.

For $x \geq 9$,

$$\text{Ai}(x) = \frac{e^{-z}v(t)}{x^{1/4}},$$

where $z = \frac{2}{3}\sqrt{x^3}$ and v is an expansion in $t = 2\left(\frac{18}{z}\right) - 1$.

For $|x| < \mathit{machine\ precision}$, the result is set directly to $\text{Ai}(0)$. This both saves time and guards against underflow in intermediate calculations.

For large negative arguments, it becomes impossible to calculate the phase of the oscillatory function with any precision and so the routine must fail. This occurs if $x < -\left(\frac{3}{2\epsilon}\right)^{2/3}$, where ϵ is the *machine precision*.

For large positive arguments, where A_i decays in an essentially exponential manner, there is a danger of underflow so the routine must fail.

4 References

Abramowitz M and Stegun I A (1972) *Handbook of Mathematical Functions* (3rd Edition) Dover Publications

5 Parameters

1: X – REAL (KIND=nag_wp) *Input*

On entry: the argument x of the function.

2: IFAIL – INTEGER *Input/Output*

On entry: IFAIL must be set to 0, -1 or 1. If you are unfamiliar with this parameter you should refer to Section 3.3 in the Essential Introduction for details.

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, if you are not familiar with this parameter, the recommended value is 0. **When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.**

On exit: IFAIL = 0 unless the routine detects an error or a warning has been flagged (see Section 6).

6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

IFAIL = 1

X is too large and positive. On soft failure, the routine returns zero. See also the Users' Note for your implementation.

IFAIL = 2

X is too large and negative. On soft failure, the routine returns zero. See also the Users' Note for your implementation.

7 Accuracy

For negative arguments the function is oscillatory and hence absolute error is the appropriate measure. In the positive region the function is essentially exponential-like and here relative error is appropriate. The absolute error, E , and the relative error, ϵ , are related in principle to the relative error in the argument, δ , by

$$E \simeq |xA_i'(x)|\delta, \epsilon \simeq \left| \frac{xA_i'(x)}{A_i(x)} \right| \delta.$$

In practice, approximate equality is the best that can be expected. When δ , ϵ or E is of the order of the *machine precision*, the errors in the result will be somewhat larger.

For small x , errors are strongly damped by the function and hence will be bounded by the *machine precision*.

For moderate negative x , the error behaviour is oscillatory but the amplitude of the error grows like

$$\text{amplitude}\left(\frac{E}{\delta}\right) \sim \frac{|x|^{5/4}}{\sqrt{\pi}}.$$

However the phase error will be growing roughly like $\frac{2}{3}\sqrt{|x|^3}$ and hence all accuracy will be lost for large negative arguments due to the impossibility of calculating sin and cos to any accuracy if $\frac{2}{3}\sqrt{|x|^3} > \frac{1}{\delta}$.

For large positive arguments, the relative error amplification is considerable:

$$\frac{\epsilon}{\delta} \sim \sqrt{x^3}.$$

This means a loss of roughly two decimal places accuracy for arguments in the region of 20. However very large arguments are not possible due to the danger of setting underflow and so the errors are limited in practice.

8 Further Comments

None.

9 Example

This example reads values of the argument x from a file, evaluates the function at each value of x and prints the results.

9.1 Program Text

```

Program s17agfe

!      S17AGF Example Program Text
!
!      Mark 24 Release. NAG Copyright 2012.
!
!      .. Use Statements ..
Use nag_library, Only: nag_wp, s17agf
!      .. Implicit None Statement ..
Implicit None
!      .. Parameters ..
Integer, Parameter          :: nin = 5, nout = 6
!      .. Local Scalars ..
Real (Kind=nag_wp)         :: x, y
Integer                     :: ifail, ioerr
!      .. Executable Statements ..
Write (nout,*) 'S17AGF Example Program Results'

!      Skip heading in data file
Read (nin,*)

Write (nout,*)
Write (nout,*) '      X          Y'
Write (nout,*)

data: Do
  Read (nin,*,Iostat=ioerr) x

  If (ioerr<0) Then
    Exit data
  End If

  ifail = -1
  y = s17agf(x,ifail)

```

```
      If (ifail<0) Then
        Exit data
      End If

      Write (nout,99999) x, y
    End Do data

99999 Format (1X,1P,2E12.3)
End Program s17agfe
```

9.2 Program Data

```
S17AGF Example Program Data
-10.0
-1.0
0.0
1.0
5.0
10.0
20.0
```

9.3 Program Results

S17AGF Example Program Results

X	Y
-1.000E+01	4.024E-02
-1.000E+00	5.356E-01
0.000E+00	3.550E-01
1.000E+00	1.353E-01
5.000E+00	1.083E-04
1.000E+01	1.105E-10
2.000E+01	1.692E-27
