# NAG Library Routine Document

## F06QPF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of *bold italicised* terms and other implementation-dependent details.

#### **1** Purpose

F06QPF performs a QR factorization (as a sequence of plane rotations) of a real upper triangular matrix that has been modified by a rank-1 update.

#### 2 Specification

```
SUBROUTINE F06QPF (N, ALPHA, X, INCX, Y, INCY, A, LDA, C, S)
INTEGER N, INCX, INCY, LDA
REAL (KIND=nag_wp) ALPHA, X(*), Y(*), A(LDA,*), C(N-1), S(N-1)
```

#### 3 Description

F06QPF performs a QR factorization of an upper triangular matrix which has been modified by a rank-1 update:

$$\alpha x y^{\mathrm{T}} + U = QR$$

where U and R are n by n real upper triangular matrices, x and y are n-element real vectors,  $\alpha$  is a real scalar, and Q is an n by n real orthogonal matrix.

Q is formed as the product of two sequences of plane rotations:

$$Q^{\mathrm{T}} = Q_{n-1} \cdots Q_2 Q_1 P_1 P_2 \cdots P_{n-1}$$

where

 $P_k$  is a rotation in the (k, n) plane, chosen to annihilate  $x_k$ : thus  $Px = \beta e_n$ , where  $P = P_1 P_2 \cdots P_{n-1}$  and  $e_n$  is the last column of the unit matrix;

 $Q_k$  is a rotation in the (k, n) plane, chosen to annihilate the (n, k) element of  $(\alpha \beta e_n y^T + PU)$ , and thus restore it to upper triangular form.

The 2 by 2 plane rotation part of  $P_k$  or  $Q_k$  has the form

$$\begin{pmatrix} c_k & s_k \\ -s_k & c_k \end{pmatrix}$$
.

The tangents of the rotations  $P_k$  are returned in the array X; the cosines and sines of these rotations can be recovered by calling F06BCF. The cosines and sines of the rotations  $Q_k$  are returned directly in the arrays C and S.

#### 4 References

None.

#### 5 Parameters

1: N – INTEGER

On entry: n, the order of the matrices U and R. Constraint:  $N \ge 0$ . Input

2:	ALPHA – REAL (KIND=nag_wp) Input
	On entry: the scalar $\alpha$ .
3:	$X(*)$ - REAL (KIND=nag_wp) arrayInput/OutputNote: the dimension of the array X must be at least max $(1, 1 + (N - 1) \times INCX)$ .On entry: the n-element vector x. $x_i$ must be stored in $X(1 + (i - 1) \times INCX)$ , for $i = 1, 2,, N$ .
	Intermediate elements of X are not referenced.
	On exit: the referenced elements are overwritten by details of the sequence of plane rotations.
4:	INCX – INTEGER Input
	On entry: the increment in the subscripts of X between successive elements of x. Constraint: INCX > 0.
5:	Y(*) – REAL (KIND=nag_wp) array Input
	Note: the dimension of the array Y must be at least $max(1, 1 + (N - 1) \times INCY)$ .
	On entry: the <i>n</i> -element vector y. $y_i$ must be stored in $Y(1 + (i - 1) \times INCY)$ , for $i = 1, 2,, N$ .
	Intermediate elements of Y are not referenced.
6:	INCY – INTEGER Input
	On entry: the increment in the subscripts of Y between successive elements of y.
	Constraint: $INCY > 0$ .
7:	A(LDA, *) – REAL (KIND=nag_wp) array Input/Output
	Note: the second dimension of the array A must be at least N.
	On entry: the $n$ by $n$ upper triangular matrix $U$ .
	On exit: the upper triangular matrix R.
8:	LDA – INTEGER Input
	On entry: the first dimension of the array A as declared in the (sub)program from which F06QPF is called.
	Constraint: $LDA \ge max(1, N)$ .
9:	C(N - 1) - REAL (KIND=nag_wp) array Output
	On exit: the cosines of the rotations $Q_k$ , for $k = 1, 2,, n - 1$ .
10:	$S(N-1) - REAL$ (KIND=nag_wp) array Output
	On exit: the sines of the rotations $Q_k$ , for $k = 1, 2,, n - 1$ .

## 6 Error Indicators and Warnings

None.

## 7 Accuracy

Not applicable.

### 8 Parallelism and Performance

F06QPF is not threaded by NAG in any implementation.

F06QPF makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the X06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this routine. Please also consult the Users' Note for your implementation for any additional implementation-specific information.

## 9 Further Comments

None.

#### 10 Example

None.